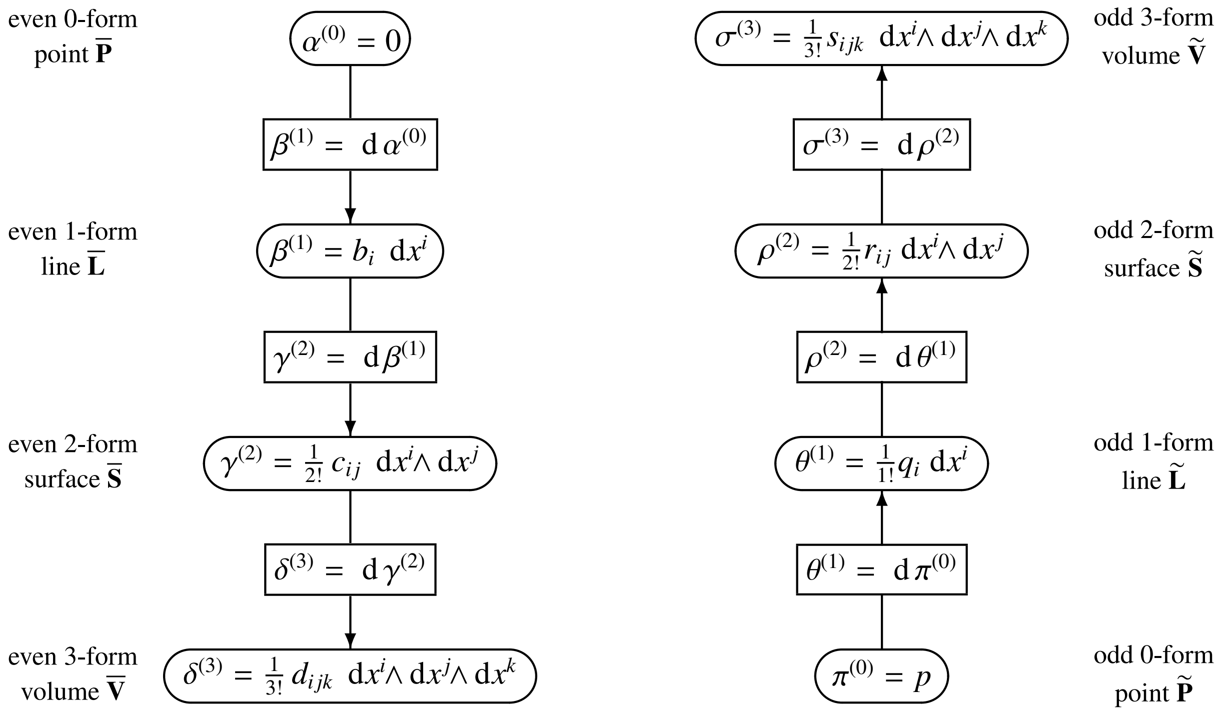
even and odd differential forms in 3D: no metric, no connexion

covariant multivectors
inner orientation: weight factor 1

covariant W-multivectors
outer orientation: weight factor $\frac{|\Lambda|}{\Lambda}$



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